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| UTS SAFE WORK METHOD statement (SWMS) |

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| 1. **FACULTY/SUBJECT** | |
| Faculty/Subject title | 41013 Industrial Robotics |
| Subject supervisor/coordinator | Gavin Paul |
| SWMS prepared by | John Shannon |

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| 1. **WORK ACTIVITY DESCRIPTION** | | | | | | |
| Describe the work activity E.g. Operating, Handling, Using.. Include names of hazardous equipment, substances or materials used,  and any quantities and concentrations of substance(s) or reaction products. | I will be working with a UR3 robotic limb with 6 links. The only equipment required for use in this project is the UR3 and a laptop. The UR3 will be performing a task as set by through the laptop which will interface to the robotic arm. Its task will be to safely move from one end-effector position to another (modelling the the picking of fruit from a tree/branch and placing inside a storage container on the back of a truck) | | | | | |
| 1. HAZARDS: Choose those hazard types that will need to have control measures in Section 4 | | | | | | |
| **Work Environment**   * Working in Remote Locations * Working Outdoors/fieldwork * Clinical/Industrial setting * Poor ventilation/Air quality * Temperature extremes * Working at Height * Slip/Trip/Fall hazards | | **Plant**   * Noise * Vibration * Working with compressed air * Lifts Hoists or Cranes * Moving parts (Crushing,friction, cut, stab, shear hazards) * Pressure Vessels or Boilers | | **Chemical**   * Hazardous Chemicals use * Skin/eye irritant * Sensitiser * Mutagen * Carcinogen * Toxic to reproduction * Aquatic toxicity * Toxic * Corrosive * Dangerous when wet | | **Ergonomic/Manual Handling**   * Repetitive or awkward movements * Lifting heavy objects * Over reaching * Working above shoulder or below knee height * Poor workstation set up |
| **Electrical**   * Plug in equipment * High voltage * Exposed wiring * Exposed conductors | | **Radiation**   * Ionising Radiation * Non-ionising radiation (Lasers, Microwaves, Ultraviolet light) | | **Biological**   * Sharps/Needles * Cytotoxins * Pathogens/infectious materials * Infectious materials * Communicable diseases * Animal/insects * Work with fungi/bact/viruses | | **Psychosocial**   * Aggressive or violent clients/students * Working in isolation * Working with timeframes * Staffing issues |
| 1. **CONTROLS MEASURES: Choose those that apply for hazards identified** | | | | | | |
| **Eliminate/Isolate/Substitute / Engineering Controls**   * Remove hazard * Restrict access * Redesign equipment * Guarding / Barriers / Fume Cupboard / exhaust * Biosafety cabinet * Use safer materials/substances * Ventilation * Regular maintenance of equipment * Redesign of workspace / workflow | | | **Admin specific: Licenses/permits Work Methods**   * Training Information or Instruction * Licensing or certification of operators * Test and tag electrical equipment * Restricted access * Regular breaks * Task rotation * Work in pairs * Document Chemical risk assessment * Ladder / Sling register | | **Emergency Response Systems**   * First aid kit * Chemical spill kit * Safety shower * Eye wash station * Emergency Stop button * Remote Communication Mechanism | |
| **Other controls not listed** | | | | | | |
| 1. **PPE REQUIRED (Tick those that apply)** | | | | | | |
| http://www.orr.uts.edu.au/images/pictograms/protection/hand.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/face.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/eye.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/hearing.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/foot.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/ppe.png | | | | | | |
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| http://www.orr.uts.edu.au/images/pictograms/protection/respiratory.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/head.pnghttp://www.orr.uts.edu.au/images/pictograms/protection/hair.png | | | | | | |
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| 1. **EMERGENCY EQUIPMENT** | | | | | | |
| http://www.orr.uts.edu.au/images/pictograms/equipment/eyewash.pnghttp://www.orr.uts.edu.au/images/pictograms/equipment/spill.pnghttp://www.orr.uts.edu.au/images/pictograms/equipment/shower.png | | | | | | |
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| 1. **work activity steps** |
| **before you start:**   * Complete safety inductions * Study documentation on UR3 robot * Create a model in matlab of the UR3 robot * Write code in matlab to control UR3 robot * Finalise UR3 control code   **steps in work activity:**   1. Turn on UR3 robot 2. Connect laptop to UR3 robot 3. Ensure area around UR3 is clear and notify bystanders 4. Run matlab code to control UR3 robot 5. Observe and record results 6. Shutdown UR3 and pack up equipment   **emergency procedures:**   * Press emergency button * Notify security or dial 6 using the UTS internal phone   **training required:**   * Mechatronics lab induction * Study resources and documentation on UR3 robot |

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| 1. **sign off** | | |
| **prepared by:**  **NAME: JOHN SHANNON** | **Lab Supervisor**  **Name: Michael Lee** | **Date: 13/10/2023**  **Review Date: 13/10/2023** |